

វិទ្យាស្ថានបច្ចេកវិទ្យាកម្ពុជា

InstitutE OF TechnologY OF CambodIA

Graduate school

Master’s Degree of Engineering

in

Mechatronics, Information and Communication Engineering

**PATH PLANNING and control OF WHEELED MOBILE ROBOT with OCCUPANCY GRID MAP**

A thesis submitted by

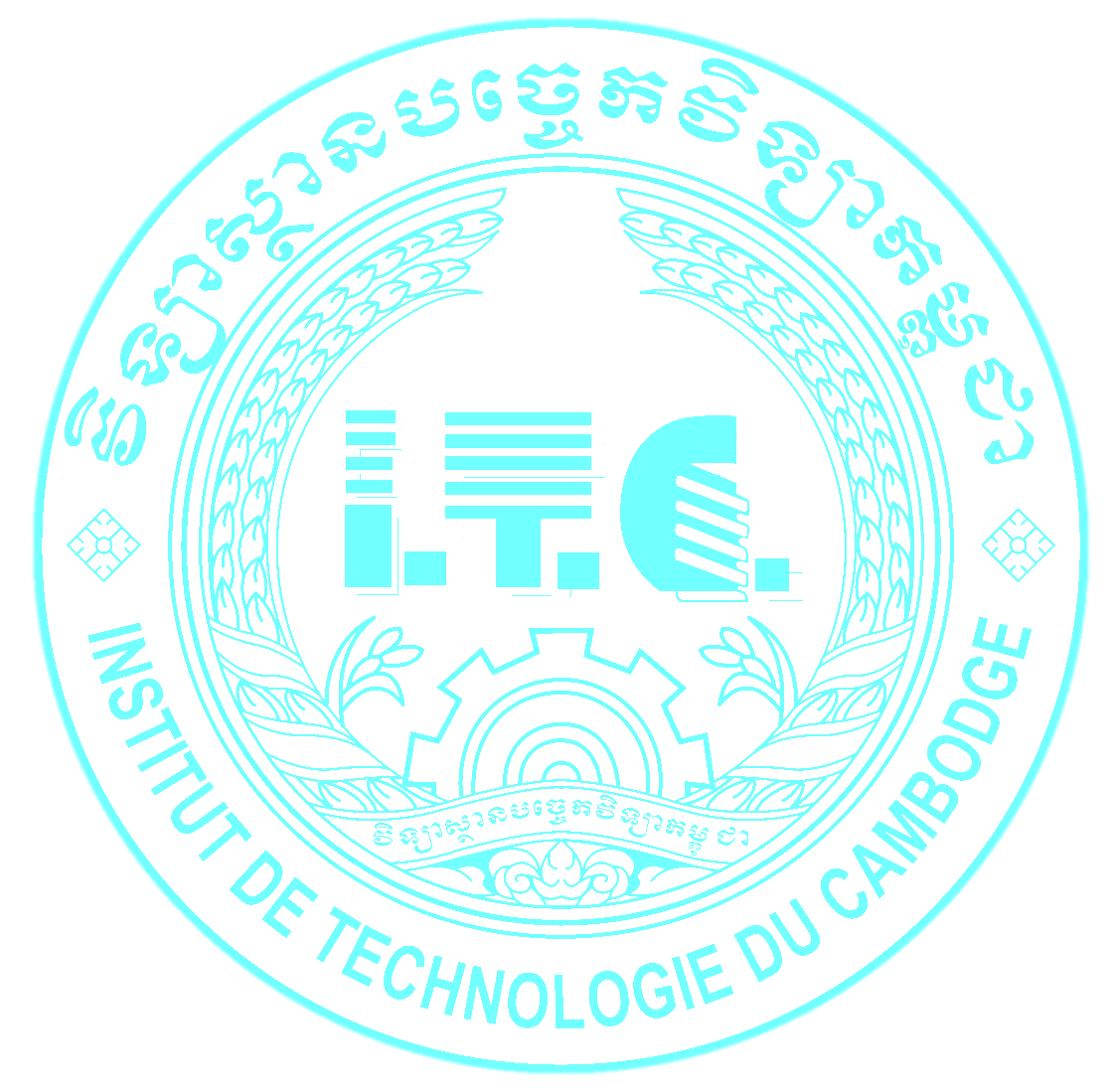
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**YONRITH Phayuth**

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MASTER’S DEGREE OF ENGINEERING

Specialization: ***Mechatronics, Information and Communication Engineering***

SUPERVISOR: **Dr. SRANG Sarot**

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